### Bayesian effect fusion for categorial predictors

### Helga Wagner joint work with Gertraud Malsiner-Walli and Daniela Pauger

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Helga Wagner

Bayesian effect fusion

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## Motivation: contributions to private retirement pension

- data on 3077 persons from EU-SILC 2010
- goal: model contributions to private retirement pension
   response=log contributions
- categorical covariates
  - age: ordinal, 11 categories (base: 16-20)
  - income class (in quartiles): ordinal, 4 levels (base: 1.quartile)
  - gender: nominal, binary (base: male)
  - child in household: nominal, binary (base: no child)
  - federal states: nominal, 9 levels (base: Upper Austria)
  - employment status: nominal, 4 levels (base: employed)
  - highest education achieved: nominal, 10 levels (base: secondary or lower)

## Linear regression model

for a categorial predictor with levels  $c \in \{0, 1, \dots, K\}$ 

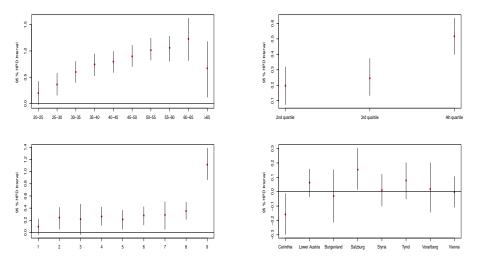
- define baseline category (e.g. *c* = 0)
- define dummy variables

$$x_k = egin{cases} 1 & ext{if } oldsymbol{c} = k \ 0 & ext{otherwise} \end{cases}$$

$$\mathbf{y} = \mu + \mathbf{x}' \boldsymbol{\beta} + \varepsilon, \quad \varepsilon \sim \mathcal{N}\left(\mathbf{0}, \sigma_{\varepsilon}^{2}\right)$$

effect of one covariate is captured by a set of K regression coefficients

## SILC data: 95% HPD-intervals



Effects of age class (upper left), income (upper right), education (lower left) and federal state (lower right)

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# Sparsity for one categorical predictor

#### Model

$$\mathbf{y} = \mu + \sum_{k=1}^{K} \mathbf{x}_{k} \beta_{k} + \varepsilon, \qquad \varepsilon \sim \mathcal{N}\left(\mathbf{0}, \sigma^{2}\right)$$

Sparsity: effect of the covariate can be modelled by less than *K* regression coefficients

- All level effects are zero. ⇒ Exclude covariate (group selection).
- Some level effects are zero. ⇒ Select level effects (within-group selection).
- Some levels have the same effect.  $\implies$  Fuse level effects.

# **Bayesian modelling**

Achieve sparsity via appropriate prior distributions

- covariance mixture of multivariate Normals (Pauger and Wagner, 2017)
  - model low or high partial correlation between effects
  - spike and slab prior on effect differences
- model based clustering of level effects (Malsiner-Walli et. al., 2017)
  - many spiky Normal components
  - sparsity is achieved by prior on the mixture weights to encourage empty components

## **Covariance Mixture of Multivariate Normals**

$$egin{aligned} eta | au^2, \delta &\sim \mathcal{N}\left(oldsymbol{0}, rac{K}{2} au^2 oldsymbol{Q}^{-1}(\delta)
ight) \ au^2 &\sim \mathcal{G}^{-1}(oldsymbol{g}_0, oldsymbol{G}_0) \end{aligned}$$

- $\mathbf{Q}(\delta)$  determines the structure of the prior precision matrix, depending on  $\delta$
- $\delta$  is a vector of binary indicators
- $\tau^2$  is a scale factor

# Prior for unrestricted effect fusion

- δ<sub>kj</sub> defined for each pair of effects 0 ≤ j < k ≤ K</li>
   ⇒ δ has (<sup>K+1</sup><sub>2</sub>) elements
- prior precision matrix

$$\mathbf{Q}(\boldsymbol{\delta}) = \begin{pmatrix} \sum_{j \neq 1} \kappa_{1j} & -\kappa_{12} & \dots & -\kappa_{1K} \\ -\kappa_{21} & \sum_{j \neq 2} \kappa_{2j} & \dots & -\kappa_{2K} \\ \vdots & \vdots & \ddots & \vdots \\ -\kappa_{K1} & -\kappa_{K2} & \dots & \sum_{j \neq K} \kappa_{Kj} \end{pmatrix}$$

• elements  $\kappa_{kj}$  depend on the corresponding indicator

$$\kappa_{kj} = \begin{cases} 1 & \text{if } \delta_{kj} = 1 \\ r >> 1 & \text{if } \delta_{kj} = 0 \end{cases}$$

and  $\kappa_{jk} = \kappa_{kj}$  for j > k.

## Structure matrix; Examples

$$K = 4: \delta = (\delta_{10}, \delta_{20}, \dots, \delta_{40}, \dots \delta_{43})$$
  
 $r = 1000$ 

$$\mathbf{Q}(\delta) = \begin{pmatrix} \mathbf{1003} & -1 & -1 & -1 \\ -1 & 4 & -1 & -1 \\ -1 & -1 & 4 & -1 \\ -1 & -1 & -1 & 4 \end{pmatrix}$$

•  $\delta_{21} = \delta_{34} = 0$ 

$$\mathbf{Q}(\delta) = \begin{pmatrix} 1003 & -1000 & -1 & -1 \\ -1000 & 1003 & -1 & -1 \\ -1 & -1 & 1003 & -1000 \\ -1 & -1 & -1000 & 1003 \end{pmatrix}$$

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## Properties of the effect fusion prior

- results from spike and slab prior on effect contrasts
  - set β<sub>0</sub> = 0 and define effect contrasts

$$\theta_{kj} = \beta_k - \beta_j$$
 for  $0 \le j < k \le K$ 

spike and slab prior

$$heta_{kj} \sim \delta_{kj} \mathcal{N}\left(\mathbf{0}, \tau^2\right) + (\mathbf{1} - \delta_{kj}) \mathcal{N}\left(\mathbf{0}, \frac{\tau^2}{r}\right)$$

• determine marginal prior for  $\beta = (\theta_{10}, \dots, \theta_{k0})$  taking into account for linear dependence

$$\theta_{kj} = \theta_{k0} - \theta_{j0}$$

 all pairs are taken into account in the same way ⇒ prior is invariant to choice of the baseline

# Marginal prior on regression effects

• joint prior on the indicators

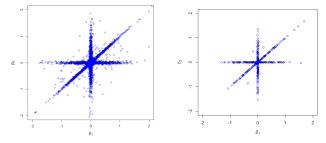
$$p(\delta) \propto |\mathbf{Q}(\delta)|^{-1/2} r^{\sum (1-\delta_{kj})/2}$$

computationally convenient as  $|\mathbf{Q}(\delta)|$  cancels out in the joint prior

prior concentrates at

$$\flat \ \beta_k = \mathbf{0}$$

• 
$$\beta_k = \beta_j$$



**Figure:** Simulation from the effect fusion prior: Plot of  $(\beta_1, \beta_2)$  for c = 3 and hyperparameters  $g_0 = 5$ ,  $G_0 = 2$ , r = 1000 (left) and r = 10000 (right)

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## Prior for restricted fusion

- no direct fusion of level effects k and j: set  $\kappa_{kj} = 0$
- examples
  - ordinal covariate: fusion restricted to adjacent categories

$$\kappa_{kj} = 0 \qquad j \neq k-1$$

$$\mathbf{Q}(\delta) = egin{pmatrix} \kappa_{10}+\kappa_{21}&-\kappa_{12}&\dots&0&0\ -\kappa_{21}&\kappa_{21}+\kappa_{32}&\dots&.&0\ dots&dots&dots&dots&dots\ dots&dots&dots&dots\ dots&dots&dots&dots&dots\ dots&dots&dots&dots&dots&dots\ dots&dots&dots&dots&dots&dots\ dots&dots&dots&dots&dots&dots\ dots&dots&dots&dots&dots&dots&dots\ dots&$$

variable selection: restrict fusion to the baseline

$$\kappa_{kj} = 0 \qquad j \neq 0$$

$$\mathbf{Q}(\delta) = \begin{pmatrix} \kappa_{10} & 0 & \dots & 0 & 0 \\ 0 & \kappa_{20} & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & \kappa_{k,0} \end{pmatrix}$$

## **Posterior inference**

- **1** MCMC: start with  $\delta = \mathbf{1}$ 
  - sample  $\beta$ 
    - **\*** compute the prior precision matrix  $\mathbf{Q}(\delta)$
    - ★ sample  $\beta$  from the conditional Normal posterior  $\mathcal{N}(\mathbf{b}_n, \mathbf{B}_n)$
  - compute the effect differences  $\theta$
  - sample  $\delta_{kj}$  from  $p(\delta_{kj}|\theta_{kj}, \tau^2)$
  - ► sample \(\tau^2\)

2 model selection: minimization of Binder's loss

$$\mathcal{L}(\mathbf{z}, \mathbf{z}^*) = \sum_{j \neq k} \left( \ell_1 \mathbf{I}_{\{z_k = z_j\}} \mathbf{I}_{\{z_k^* \neq z_j^*\}} + \ell_2 \mathbf{I}_{\{z_k \neq z_j\}} \mathbf{I}_{\{z_k^* = z_j^*\}} \right)$$

where **z** is the true and **z**<sup>\*</sup> the proposed clustering

refit of the selected model (with fused levels)

# Simulation Study

Set-up:

- 100 data sets of size N = 500
- four ordinal  $C_1, \ldots, C_4$  and four nominal predictors  $C_5, \ldots, C_8$
- covariate effects
  - ▶ relevant ordinal:  $\beta_1 = (0, 1, 1, 2, 2, 4, 4)$ ,  $\beta_3 = (0, -2, -2)$
  - ▶ relevant nominal:  $\beta_5 = (0, 1, 1, 1, 1, -2, -2), \beta_7 = (0, 2, 2)$
  - irrelevant:  $\beta_2 = \beta_6 = (0, 0, 0, 0, 0, 0, 0)$ ,  $\beta_4 = \beta_8 = (0, 0, 0)$

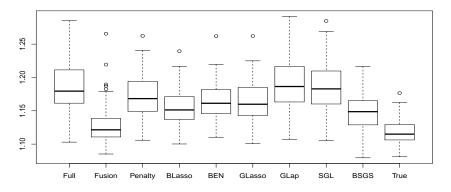
#### Results

- both zero and non-zero effect differences are identified well
- lower averaged MSE (than in the full model and other methods)
- predictive performance only slightly worse than in the true model

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## Simulation: Predictive Performance

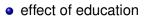
- new data set of 500 observations from the regression model
- prediction of new observations using the selected model and parameters estimated in each of the 100 data sets

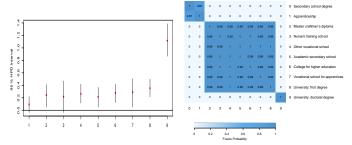


#### Mean squared prediction error

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# **EU-SILC: Results**





#### • final model: same fit but sparser

- 11 regression effects (full model: 35)
- $\hat{\sigma}^2 = 0.829$  almost identical to the full model (0.826)
- BIC: 8240.69 (full model: 8402.00)

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# Sparse finite mixture prior

### Model

$$\mathbf{y} = \boldsymbol{\mu} + \sum_{k=1}^{K} \mathbf{x}_k \boldsymbol{\beta}_k + \boldsymbol{\varepsilon}$$

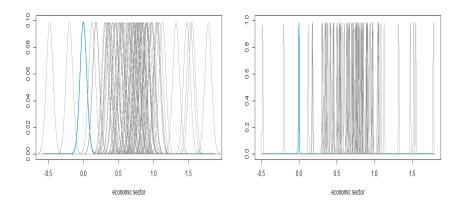
• prior distribution on the regression effects

$$p(\beta_k) = \sum_{l=0}^{L} \eta_l \, p(\beta_k | \mathcal{N}(\mu_l, \psi_l))$$
  
$$\eta \sim \mathcal{DIR}(e_0, \dots, e_0)$$
  
$$\mu_0 = 0; \quad \mu_l \sim \mathcal{N}(m_{l0}, M_{l0}) \quad l = 1, \dots L \text{ (e.g. } L = K)$$

• sparsity is achieved by small *e*<sub>0</sub> (e.g. 0.001)

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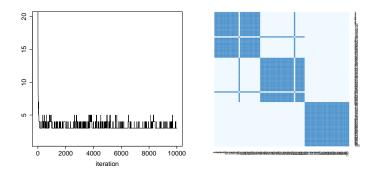
# Sparse finite mixture priors



Finite mixture prior for level effects of covariate economic sector  $\psi = 100$  (left plot) and  $\psi = 10000$  (right plot). One component is centred at zero (dashed), the others at  $\hat{\beta}_{jk}$ ,  $k = 1, \ldots c_j$ .

# Simulation study

- Setup similar to the application in order to tune the prior parameters.
- N = 4000, covariates:  $x_1$  (10 categories),  $x_2$  (100 categories).



Simulation study, one data set: Trace plot of the number of nonempty groups during MCMC sampling for variable  $x_2$  (left), and visualization of the most frequent model (right).

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## Conclusions

prior distributions for effect fusion

- covariance mixture of multivariate Normals spike and slab prior distribution on effect contrasts
- finite mixture prior location mixture of normals with small variance
- Bayesian estimation
  - feasible by MCMC methods
  - "add on" for regression type models with normal priors
- pros
  - covariance mixture: simple implementation of restricted fusion
  - sparse finite mixture prior allows finer resolution
- R-package effectFusion

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## Future research

- extension to generalized linear models (straightforward)
- sparse modelling in more general models
  - multinomial logit models

$$P(Y=r) = \frac{\exp(\boldsymbol{x'}\beta_r)}{1 + \sum_{s=1}^{R} \exp(\boldsymbol{x'}\beta_s)} \qquad r = 1, \dots, R$$

 $\beta_{rk}$  is the effect of predictor category k on response category r

- \* sparsity with respect to the predictor  $\beta_{rk} = \beta_{rk'}$
- ★ sparsity with respect to the response  $\beta_{rk} = \beta_{r'k}$
- item response models with differential item functioning
- generalized regression models for location, scale and shape

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### References

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